

buildkitboards

Using the Voyager Remote

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Written By: Jared Ebersole



FW >>



42.0V



H

18.6 mph

M

34.61A

14.62mi

 **TOOLS:**

- [Hand](#) (1)
-

Step 1 — Turning the remote on/off



- Press and hold the POWER button (left) to turn the remote on
- Press and hold the POWER and SETTINGS button to turn the remote off
- Press and hold the SETTINGS button to enter the settings menu

Step 2 — Acceleration / Brake / Reverse



- To accelerate, press the joystick forward
- To brake press the joystick backwards
- To go into reverse, hold the joystick all the way back and press the SETTINGS button

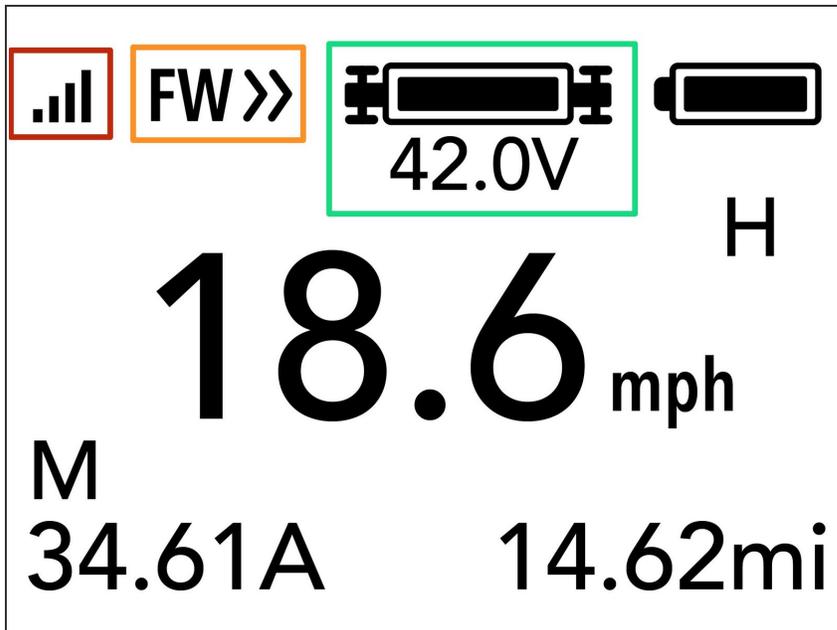
Step 3



⚠ When the receiver is plugged into the ESC it will cause UART interference resulting in programming issues. If you have issues, disable the UART communication temporarily by going to **SETTINGS -> PORTS CONFIG -> UART To ESC -> OFF**

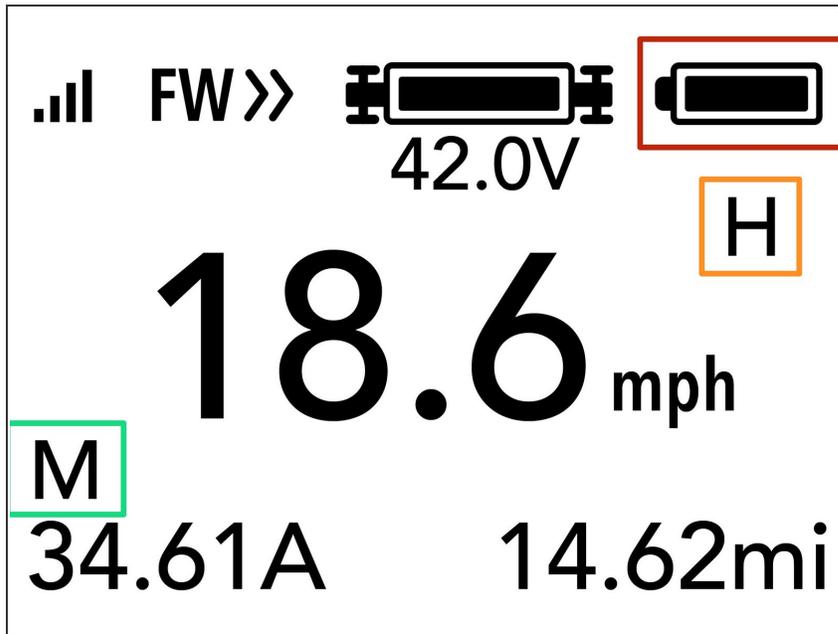
- When you are done programming, change the value back To ESC A

Step 4



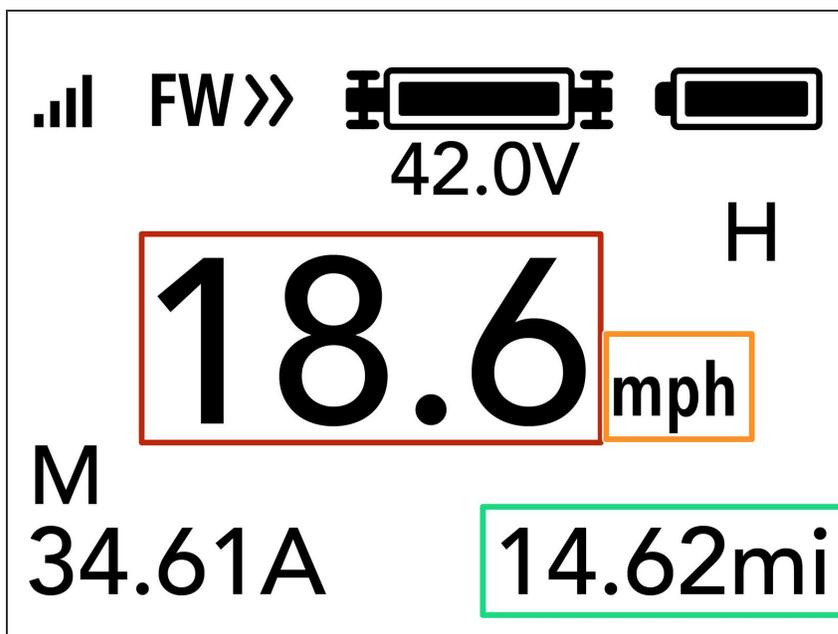
- This indicates the remote to receiver connection status. When connected it will appear
- This indicated the boards direction. It will either display FW>> for forwards or RW>> for reverse
- This indicates the skateboards battery level. If you think the values are wrong, double check your battery settings in the board parameters menu

Step 5



- Indicated the remotes battery level
- Indicates the acceleration mode. Either H, M, or L. You can change the acceleration values in the remote config menu
- Changes from M to B occasionally to indicate the value below. M stands for MOTOR current and B stands for BATTERY current.

Step 6



- Indicates the current speed
- Can either be mph or kmh. Change the value in the board parameters menu
- Total trip distance. View your lifetime odometer by viewing the remote config menu

Step 7 — Safety Features



- When turning the remote on you will not be able to apply throttle for a short period of time. To skip this, apply full brake and then you can begin to use the throttle